GENERAL CUDA TIPS

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NVIDIA LIBRARIES

cuBLAS

- Generalized BLAS package that runs on GPU
- Highly performance tuned (never write your own BLAS kernels)

cuSPARSE

- Performant sparse matrix multiplication library
- Supports fully sparse and mixed (i.e., sparse and dense) operations

cuSOLVER

Performant solvers for dense and sparse matrices

cuRAND

- Performant GPU-oriented random number generation
- Callable both in-kernel and via host code

cuFFT

- Performant GPU FFT with FFTW-style interface
- Supports multi-gpu and asynchronous computation

cuDNN

- GPU-accelerated library of ML primitives
- Highly performance tuned

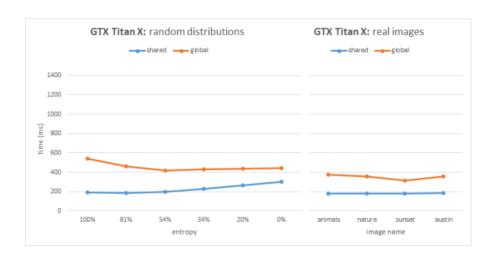
USEFUL OPERATIONS

- Warp Shuffle
 - Fast way to exchange data within a warp
 - Helps avoid __syncthreads() calls
 - Helps simplify code significantly

```
__inline__ __device__
int warpAllReduceSum(int val) {
   for (int mask = warpSize/2; mask > 0; mask /= 2)
      val += __shfl_xor(val, mask);
   return val;
}
```

Shared Memory Atomics

- Normal atomic operations just to shared memory
- Much faster than global memory atomics
- Available on Maxwell and later GPUs



NUMBA

- Essentially just CUDA in Python
- Easy interop with Numpy
- Can be used through Jupyter (i.e., Google Colab)
- Provides bindings to Nvidia APIs through pyculib
 - pyculib provides:
 - cuBLAS
 - cuSPARSE
 - cuRAND
 - cuFFT

```
@cuda.jit('void(double[:, :], double[:,:], double[:, :])')
def numba_matmul(a, b, c):
    row = cuda.threadIdx.y + cuda.blockIdx.y * cuda.blockDim.y
    col = cuda.threadIdx.x + cuda.blockIdx.x * cuda.blockDim.x

if row < a.shape[1] and col < b.shape[1]:
    val = 0.0
    for i in range(a.shape[1]):
        val += a[row][i] * b[i][col]
    c[row][col] = val</pre>
```

```
[3] a = np.random.randn(1024, 1024)
b = np.random.randn(1024, 1024)
```

```
[4] %%timeit
c = np.matmul(a, b)

10 loops, best of 5: 64.3 ms per loop
```

```
[6] %%timeit
    c = np.zeros((1024, 1024))
    numba_matmul[(32, 32), (32, 32)](a, b, c, 1024, 1024, 1024)

10 loops, best of 5: 34.9 ms per loop
```

MISC. TIPS

- Pay attention to block and grid dimensions
 - Well-dimensioned kernels can be a lot faster
 - Different kernels might need different block shapes
- Avoid atomic operations when possible
 - Atomic operations and __syncthreads() are slow!
- Pay attention to memory
 - Most kernels are memory bandwidth limited
 - Try to do a "good amount" of work for the input data

- Use the Nvidia APIs
 - They are highly optimized for most operations
- Avoid premature optimization
 - Start simple, then improve iteratively
 - Don't optimize things that don't matter
- Enable –03 on your compiler!

QUESTIONS?